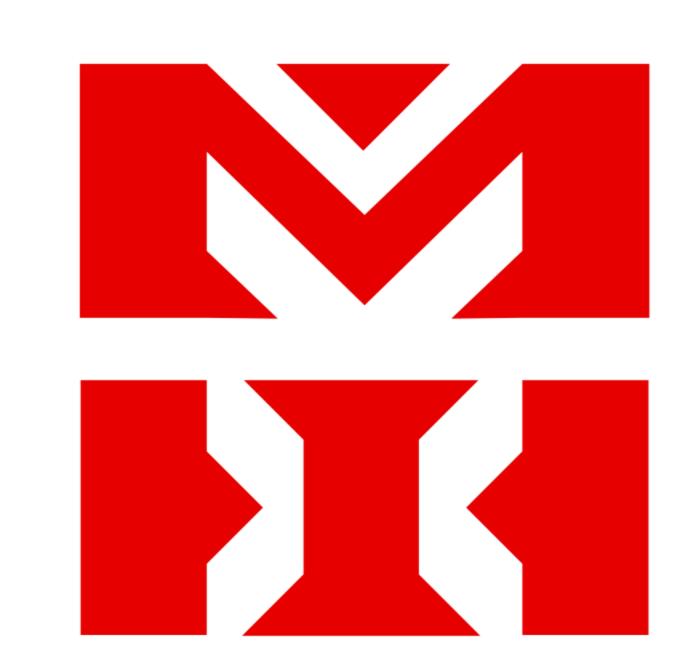
Medius 50-2100

6-Axis Industrial Robot Arm



Robust and Durable Design

All joints use precision cycloidal reducers made in Taiwan Cast iron construction



Ease of use

Web-based user-friendly interface
Operatable on teach pendant, computer and mobile devices

Ease of maintenance

Minimum use of proprietary parts

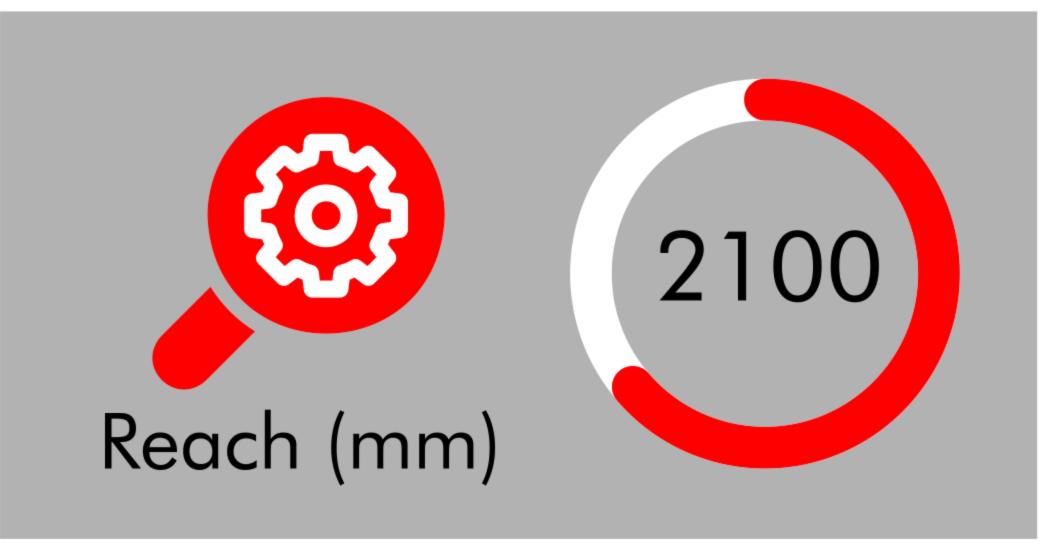
Pain-free part replacement and low long term operation cost

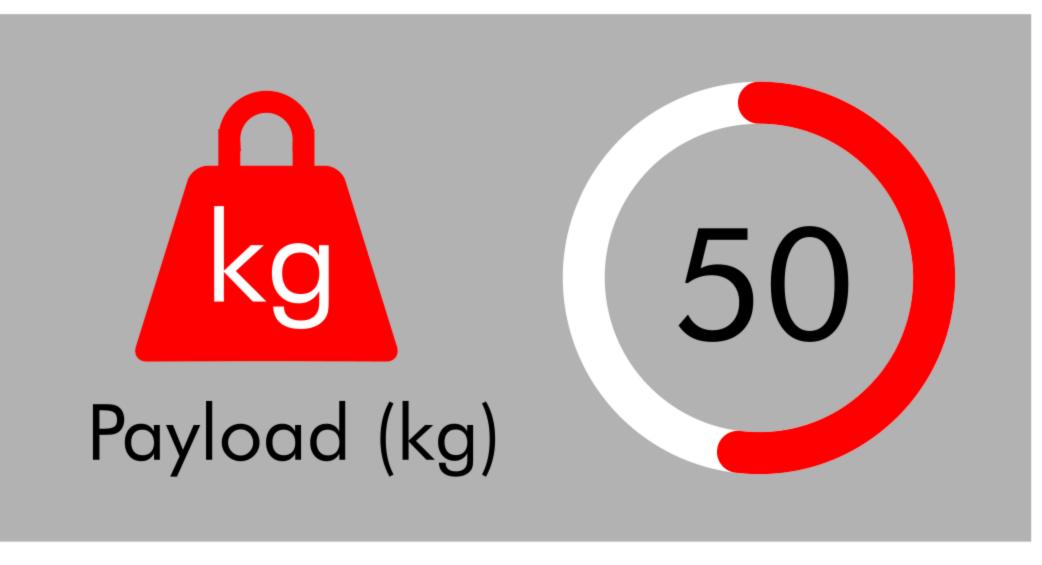
Industrial 4.0

Modbus TCP communication with production line
Plug and play for numerous applications
Built-in server for production data collection and big data

Safety First

Safety controller and dual channel protective circuits Easy integration with 3rd party safety devices







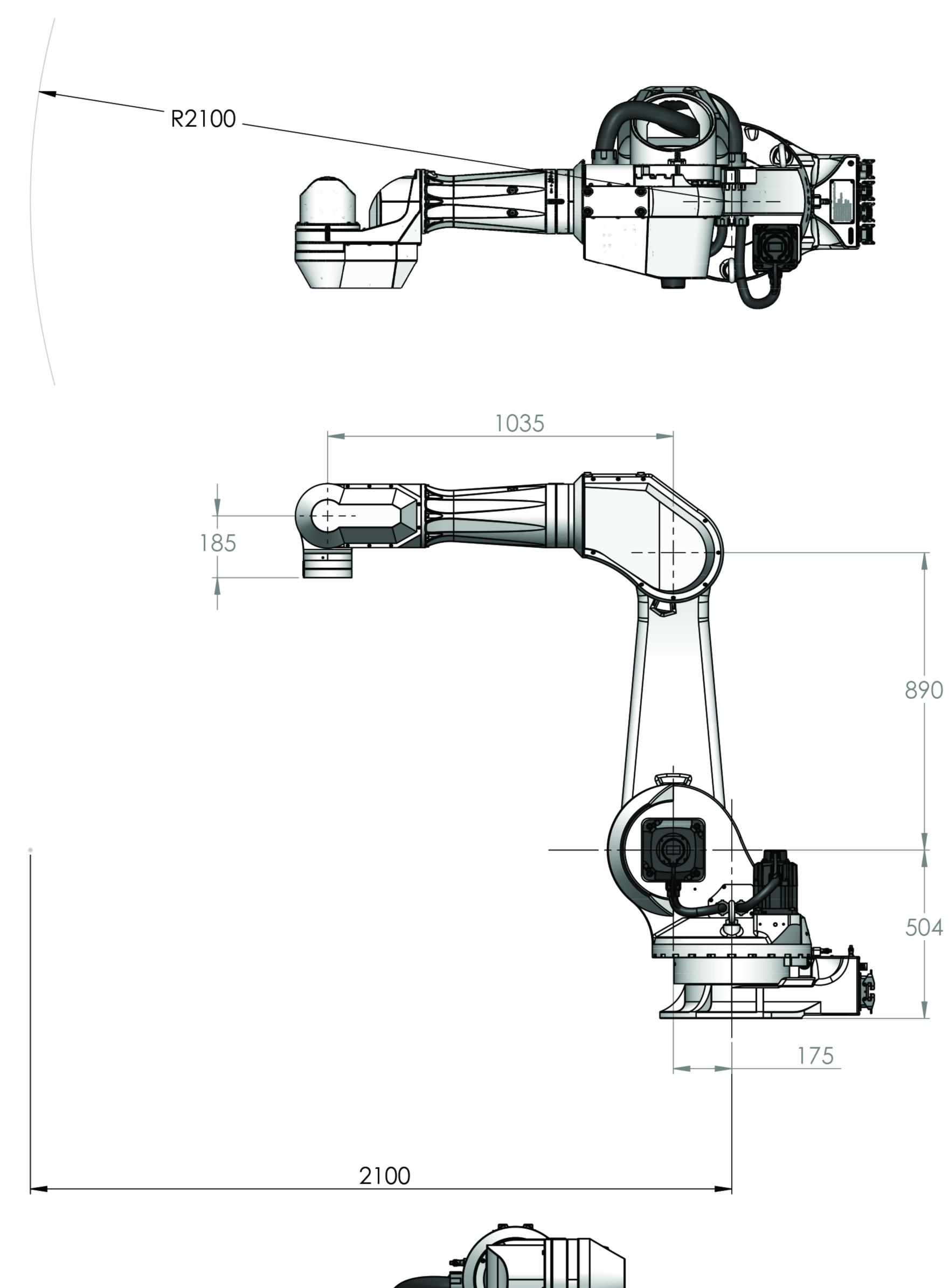
Medius 50-2100

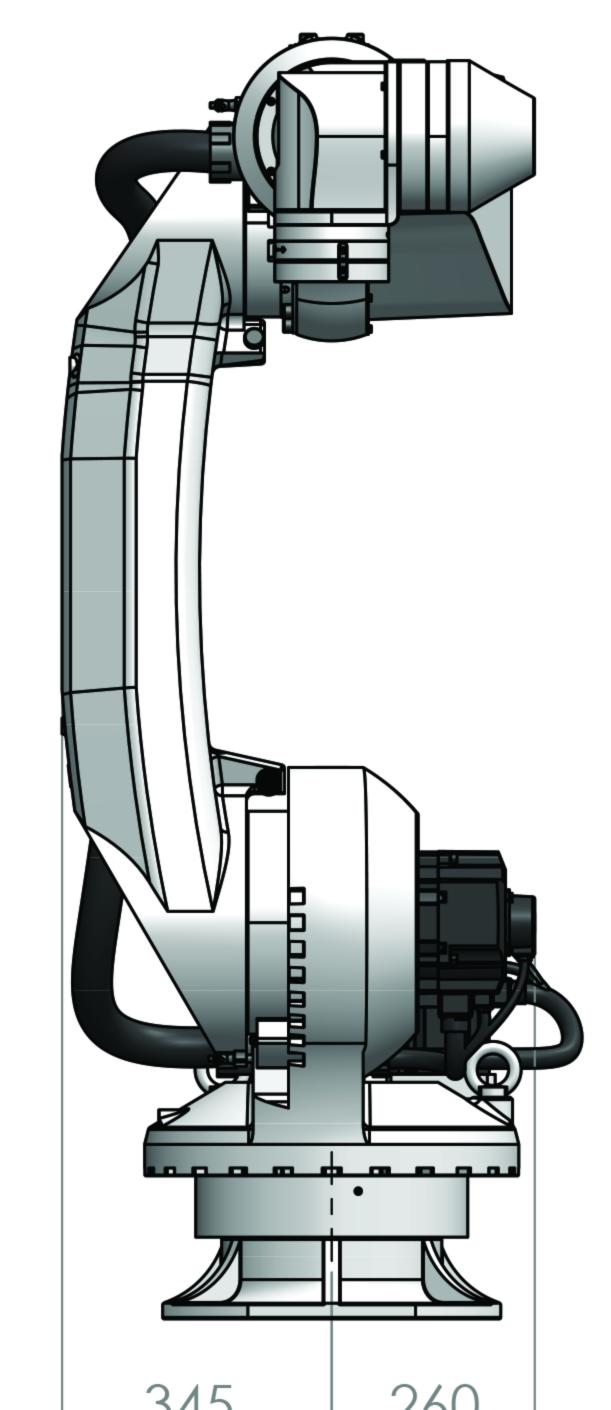
6-Axis Industrial Robot Arm

Robot Specifications

Specification Item Medius 50-2100 Model Articulated robot Robot type 6 Number of axis AC servo system Drive system 50kg Max payload 2100mm Reach ±0.06mm Repeatability Floor installation Mount 720kg Robot mass Handling, machine tending, Application palletizing, dispensing and more Modbus TCP and OPC UA Communication protocol Taiwan designed self-developed Controller embedded Linux solution robot controller EtherCAT servo motion control **Motion Control** protocol Precision cycloidal reducer Gear Reducer Made in Taiwan Dual channel safety circuit in Safety accordance with ISO 10218-1, controller ISO 13849-1 PL d

Product Dimensions





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^{*}The specifications are subjected to change without prior notice